## **PGC-50**

Collaborative parallel grippers





Gripping force(per jaw)

15~50 N

Opening/closing stroke(both sides) 35 mm

Mechanical specifications

Maximum recommended load*	1 kg
Position repeatability (both sides)	$\pm$ 0.03 mm
Opening/closing time	0.7 s/0.7 s
Driving method	Rack and pinion + T-slot guidance
Weight	0.5 kg
Noise emission	< 50 dB

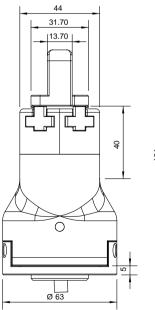
## Electrical specifications

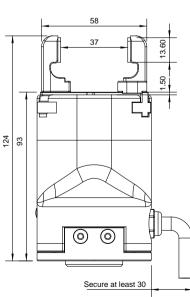
Communication Standard: Modbus RTU (RS485), Digital I/O interface Optional: TCP/IP, USB2.0, CAN2.0A, PROFINET, EtherCAT

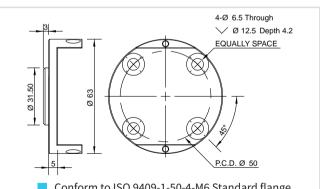
Nominal voltage	24 V DC $\pm$ 10%
Nominal current	0.25 A
Peak current	0.5 A
Ingress protection rating	IP 54
Recommended operating	0~40°C,85% RH under

## Recommended operating environmen

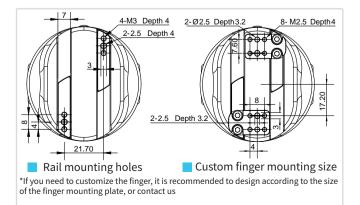
'It depends on the shape of the grasping object, the material and friction of the contact surface, and the acceleration of the motion, If you have any questions, please consult us.

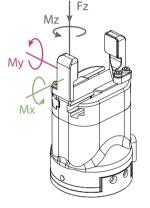






Conform to ISO 9409-1-50-4-M6 Standard flange \*If you need to customize the flange, it is recommended to design according to the robot installation hole position, or contact us





Allowable vertical load (static)		
Fz:	150 N	
Allowable vertical load (static)		
Mx:	2.5 N · m	
My:	2 N · m	
Mz:	3 N · m	